

Amendments to the Claims:

Cancel claims 25 and 26, without prejudice.

This listing of claims will replace all prior versions, and listings, of claims in the application:

Listing of Claims:

1-23. (cancelled)

24. (currently amended): An A door operator, comprising:

a door operating element;

a piston coupled to the door operating element and movable in a cylinder so as to define first and second cylinder chambers formed at respective opposite piston ends;

a spring mounted in the second cylinder chamber and biasing the piston towards the first cylinder chamber so as to have the door operating element hold a door closed;

an electrohydraulic servo drive for operating a door, the drive comprising a hydraulic circuit for holding the door open, the hydraulic circuit comprising a hydraulically controlled hold-open valve configured with a 2/2-way directional lockable non-return control valve operable for displacing the piston towards the second cylinder chamber so as to have the door operating element hold the door open.

25. (cancelled)

26. (cancelled)

27. (currently amended): An electrohydraulic servo drive as in The door operator of claim 24, wherein the 2/2-way directional lockable control valve is a slide valve.

28. (currently amended): An electrohydraulic servo drive as in The door operator of claim 25 24, wherein the hold-open valve further comprises a control piston and a non-return valve.

29. (currently amended): ~~An electrohydraulic servo drive as in The door operator of~~ claim 28, wherein at least one of said control piston and said non-return valve is spring loaded.

30. (currently amended): ~~An electrohydraulic servo drive as in The door operator of~~ claim 24, comprising a piston which moves in a piston space to operate the door, wherein the piston ~~spac~~ ~~being~~ ~~is~~ subjected to a hydraulic pressure which is greater than the ~~a~~ control pressure in the hold-open valve.

31. (currently amended): ~~An electrohydraulic servo drive as in The door operator of~~ claim 28, wherein the 2/2-way directional lockable control valve has a sealing surface, the control piston having an effective piston surface which is larger than the sealing surface of the 2/2-way directional lockable control valve.

32. (currently amended): ~~An electrohydraulic servo drive as in The door operator of~~ claim 24, wherein the hydraulic drive circuit comprises a pump driven by a motor, wherein the motor is one of a DC motor, an electronically commutated motor, a speed-controlled AC motor, and a speed-controlled 3-phase motor.

33. (currently amended): ~~An electrohydraulic servo drive as in The door operator of~~ claim 24, wherein the hydraulic drive circuit comprises means for separating forward flow and return flow.

34. (currently amended): ~~An electrohydraulic servo drive as in The door operator of~~ claim 28, wherein the non-return valve is integrated into the control piston.

35. (currently amended): ~~An electrohydraulic servo drive as in The door operator of~~ claim 28, wherein the non-return valve is provided in a bypass around the 2/2-way directional lockable control valve.

36. (currently amended): ~~An electrohydraulic servo drive as in The door operator of~~ claim 24, wherein the hydraulic ~~circuit~~ drive comprises at least one throttle valve in flow communication with the first cylinder chamber and the 2/2-way directional lockable control valve for controlling ~~at least one of opening and closing movement of the piston towards the first cylinder chamber~~.

37. (currently amended): ~~An electrohydraulic servo drive as in The door operator of~~ claim 32, wherein the pump produces hydraulic pressure for controlling the hold-open 2/2-way directional lockable control valve.

38. (currently amended): ~~An electrohydraulic servo drive as in The door operator of~~ claim 28, further comprising an adjustable valve installed parallel to bridging hydraulic lines connecting the 2/2-way directional lockable control hold-open valve to the first chamber and to the pump, respectively, for adjusting the leakage flow at the control piston so that the switching speed of the 2/2-way directional lockable control valve can be controlled.

39. (currently amended): ~~An electrohydraulic servo drive as in The door operator of~~ claim 38, wherein the adjustable valve comprises a closing body acting on a spring so that the adjustable valve closes as a function of hydraulic pressure and reduces leakage flow during opening of the door.

40. (currently amended): ~~An electrohydraulic servo drive as in The door operator of~~ claim 38, further comprising a hydraulic line leading from a pump and a hydraulic line leading to a tank space, the adjustable valve being provided between the hydraulic lines.

41. (currently amended): ~~An electrohydraulic servo drive as in The door operator of~~ claim 32 24, further comprising an auxiliary device for performing a support function during actuation of the door operating element a door, the support auxiliary device comprising a motor amplifier connected to the motor.

42. (currently amended): ~~An electrohydraulic servo drive as in The door operator of~~ claim 42 41, wherein the motor amplifier controls the motor speed by pulse width modulation.

43. (currently amended): ~~An electrohydraulic servo drive as in The door operator of~~ claim 41, further comprising a controller/current regulator for the motor amplifier.

44. (currently amended). ~~An electrohydraulic servo drive as in The door operator of~~ claim 43, further comprising a voltage supply connected to the controller/current regulator and the motor amplifier.

45. (currently amended): ~~An electrohydraulic servo drive as in The door operator of~~ claim 43 41, wherein the door operating element comprises ~~further comprising~~: a pinion driven by ~~a~~ the piston to operate the door, and a position sensor which cooperates with the pinion, wherein the controller/current regulator is connected to the position sensor.

46. (currently amended): ~~An electrohydraulic servo drive as in The door operator of~~ claim 43, wherein the controller/current regulator comprises a D/A converter.